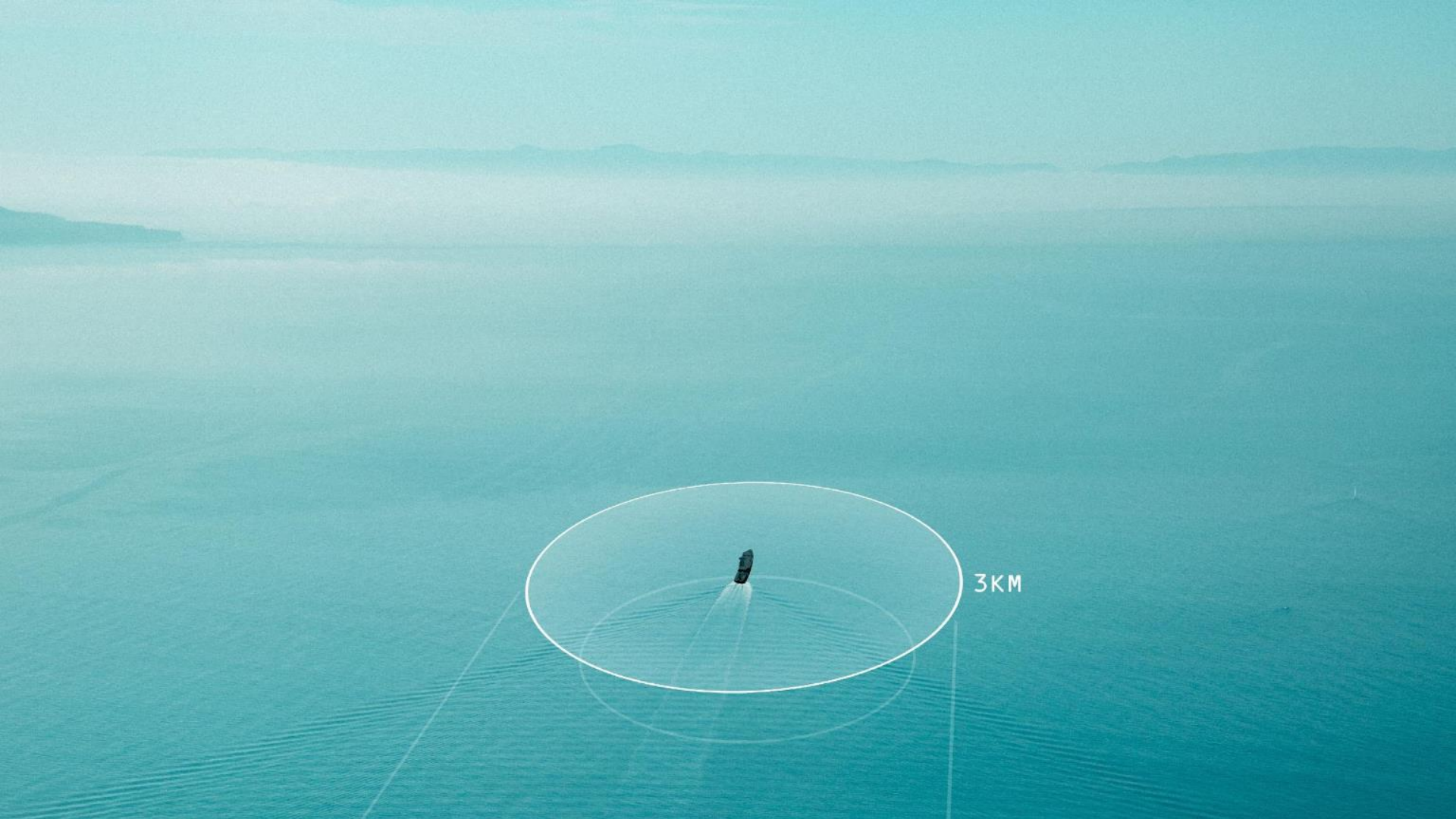


Airborne drones with probes for cost effective ocean monitoring

Mohibb Malik, Birdview AS

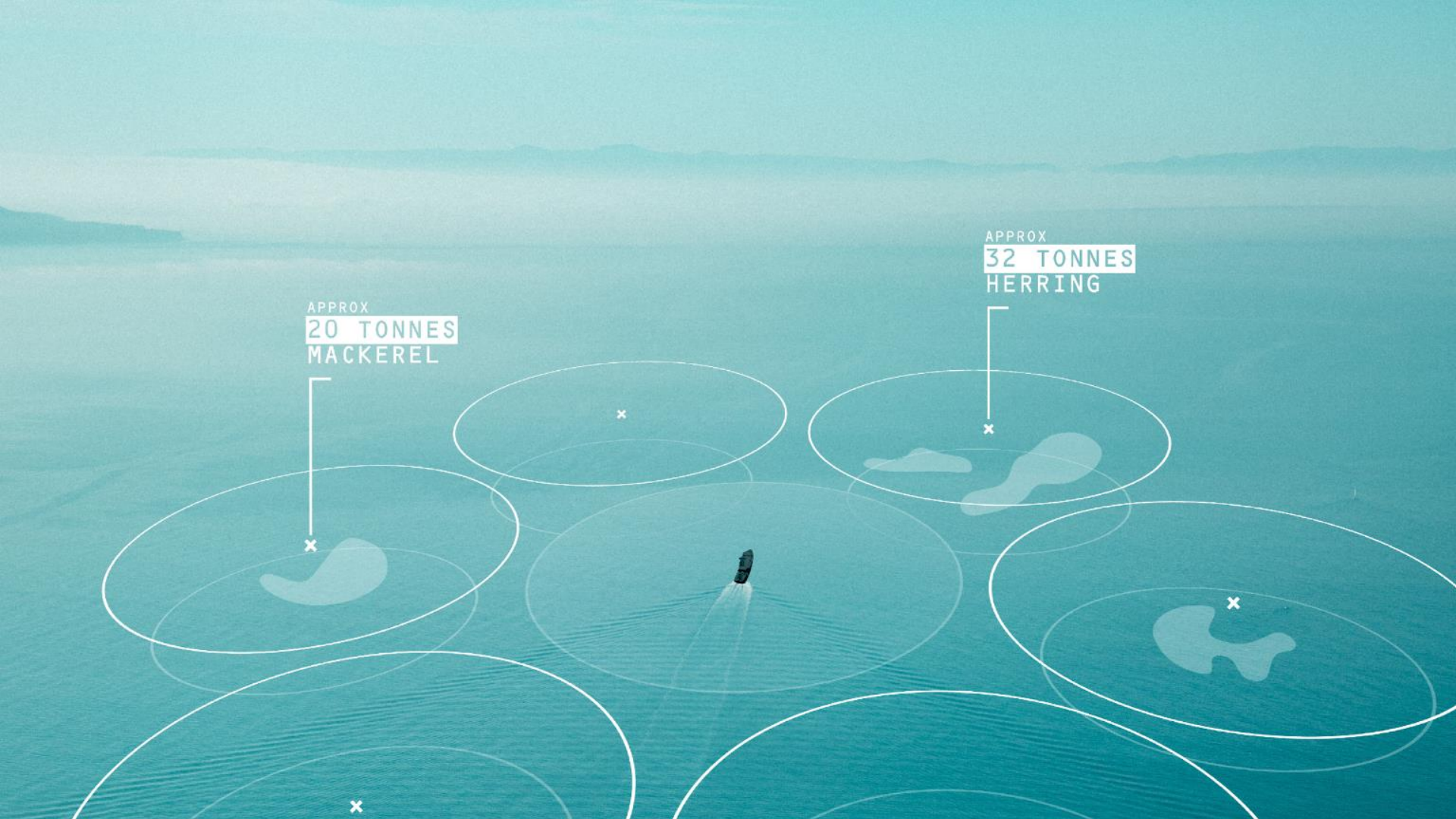


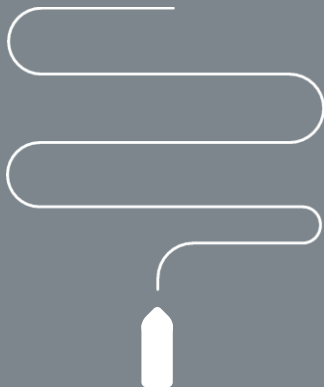


3KM

APPROX
20 TONNES
MACKEREL

APPROX
32 TONNES
HERRING

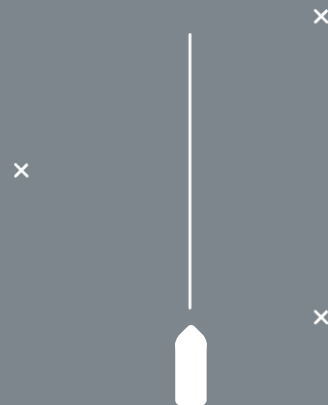




Traditional methods

Operating costs for fishing vessels are largely made up of fuel and time

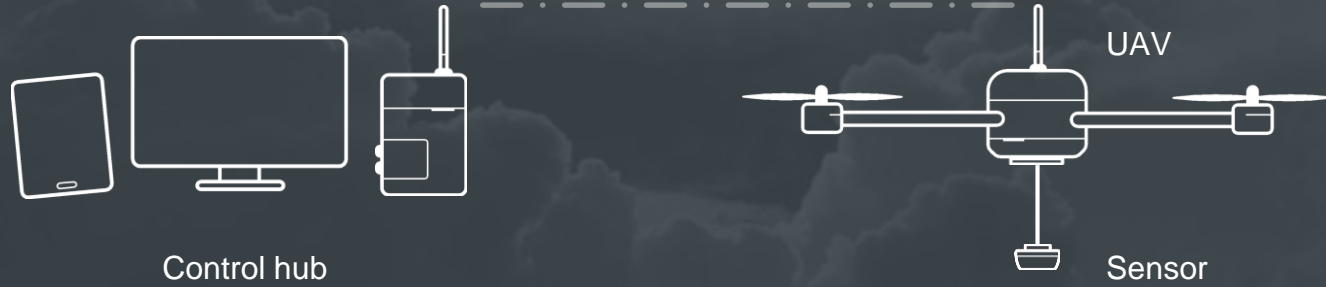
Noisy engines disturb hull mounted equipment which results in inaccurate readings



With the Birdview system

Can cover **large areas** in **short time** while using very **little fuel**

The UAVs can give **more accurate** readings when it operates far away from noisy ship engines and other interferences



The Team



Pouyan H. Shariffiasl
Founder & coordinator



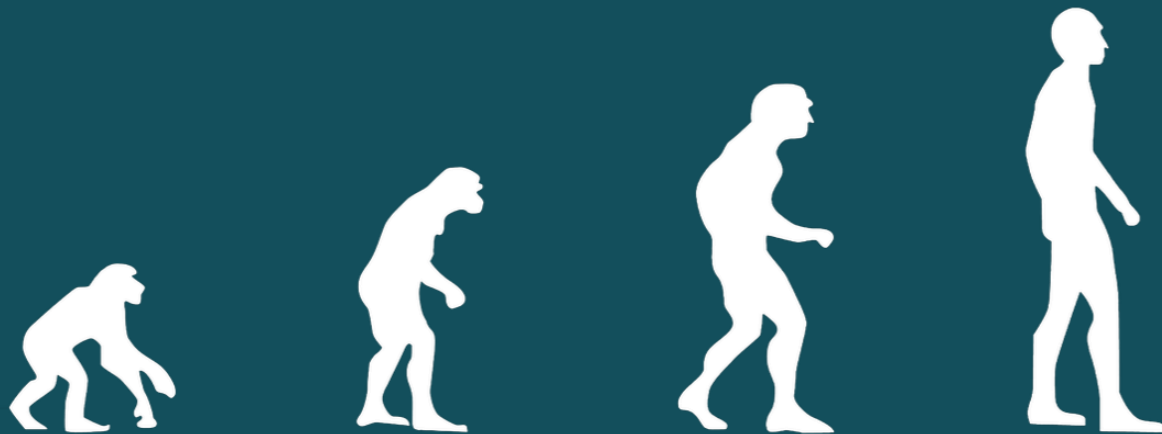
Terje Vanvik
COO, ATPL licensed pilot



Mohibb Malik
Naval engineer



Magnus Sørli
Developer/technician

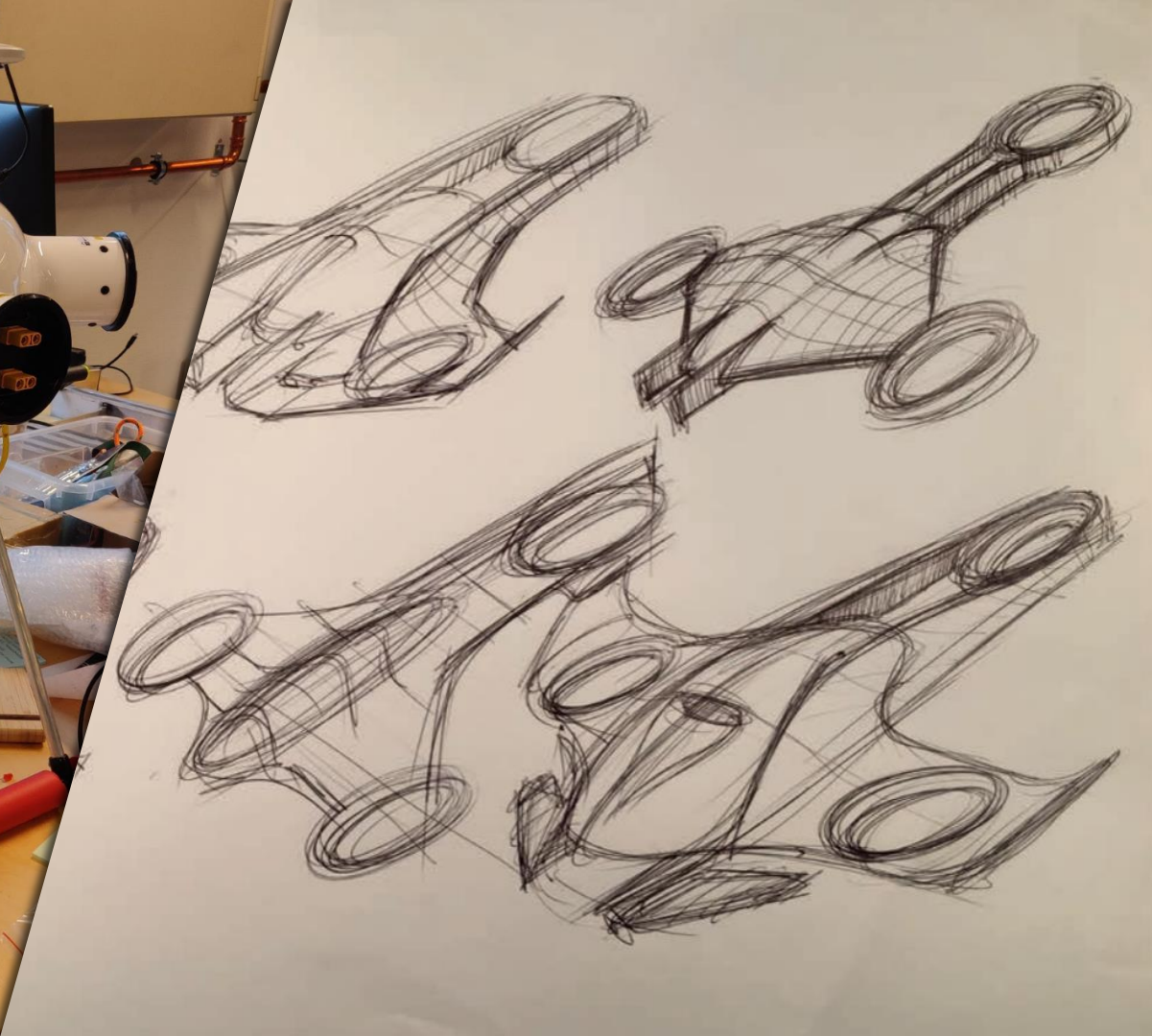
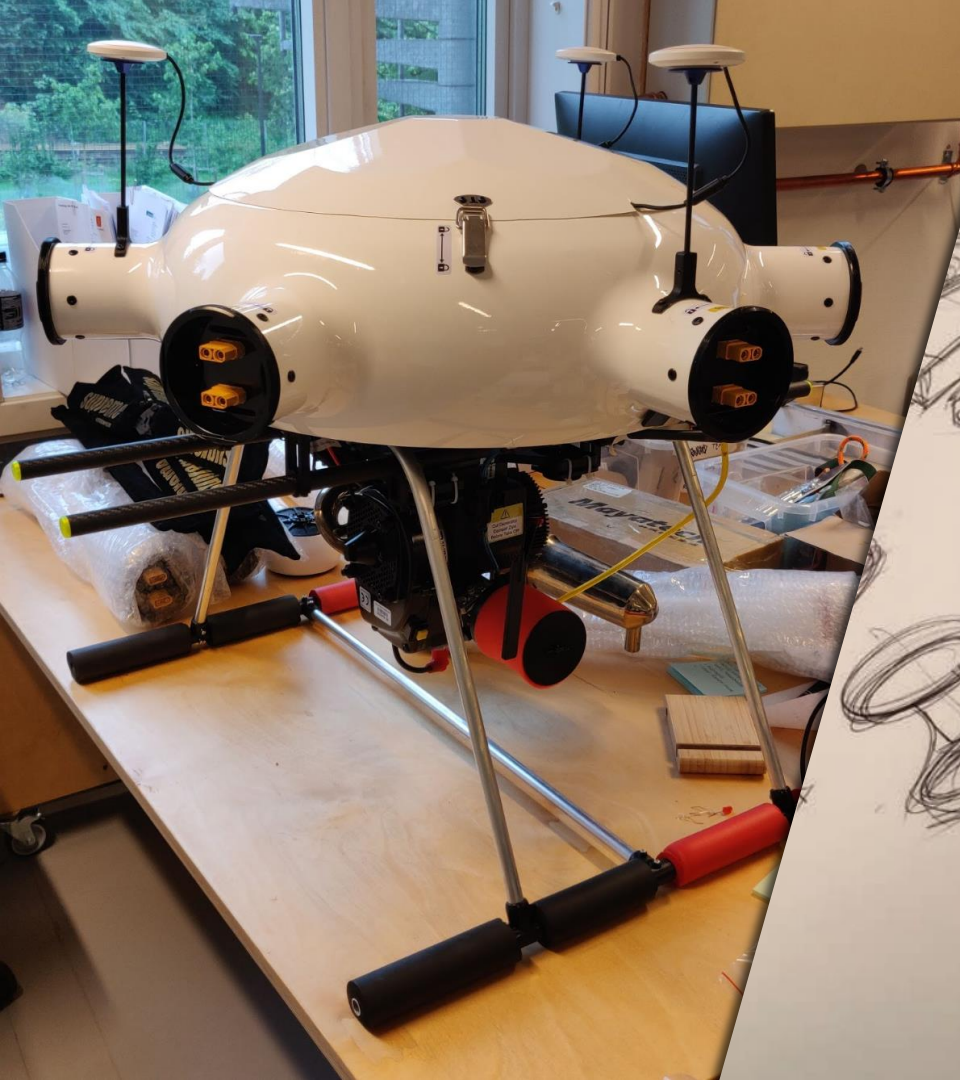


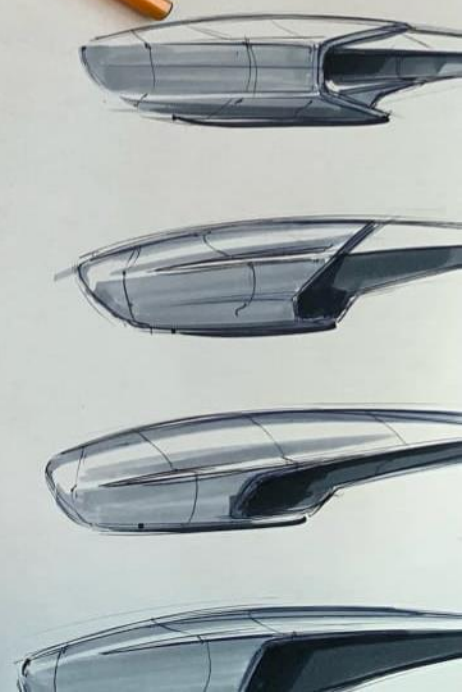
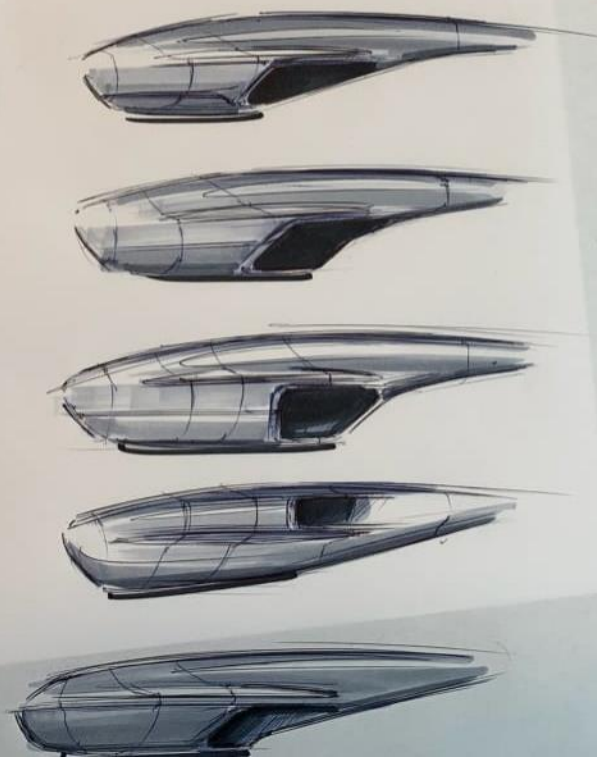
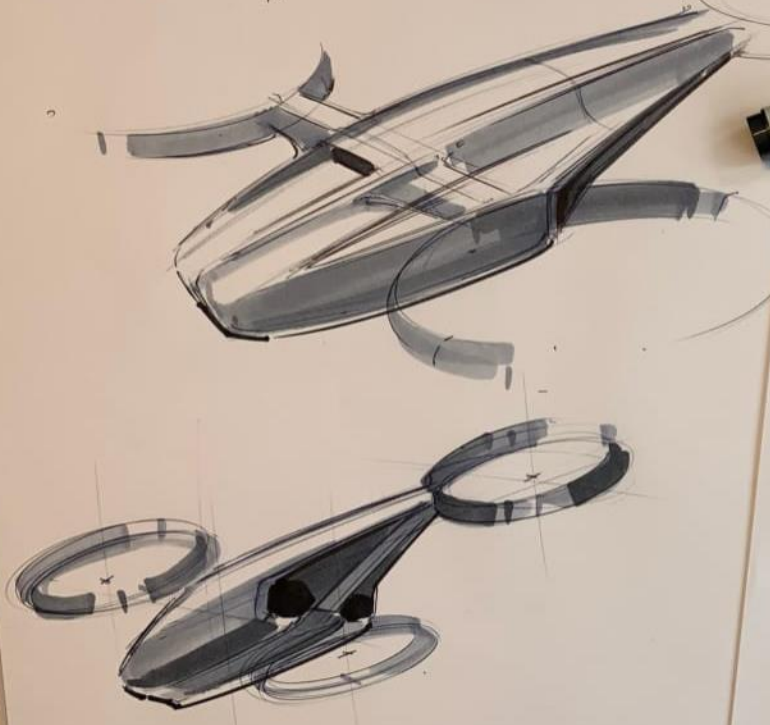
Manual takeoff/landing,
Manual operation

Autonomous takeoff/landing,
Autonomous operation



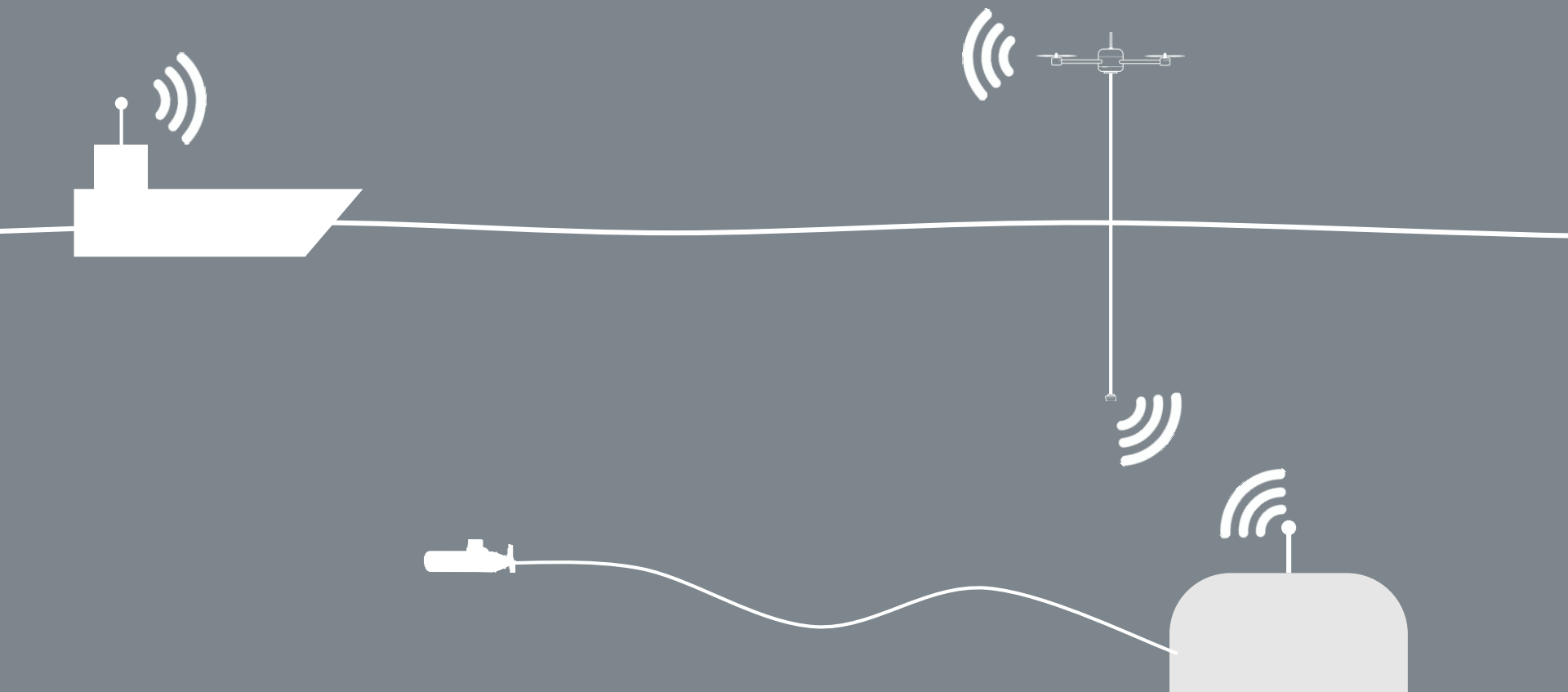


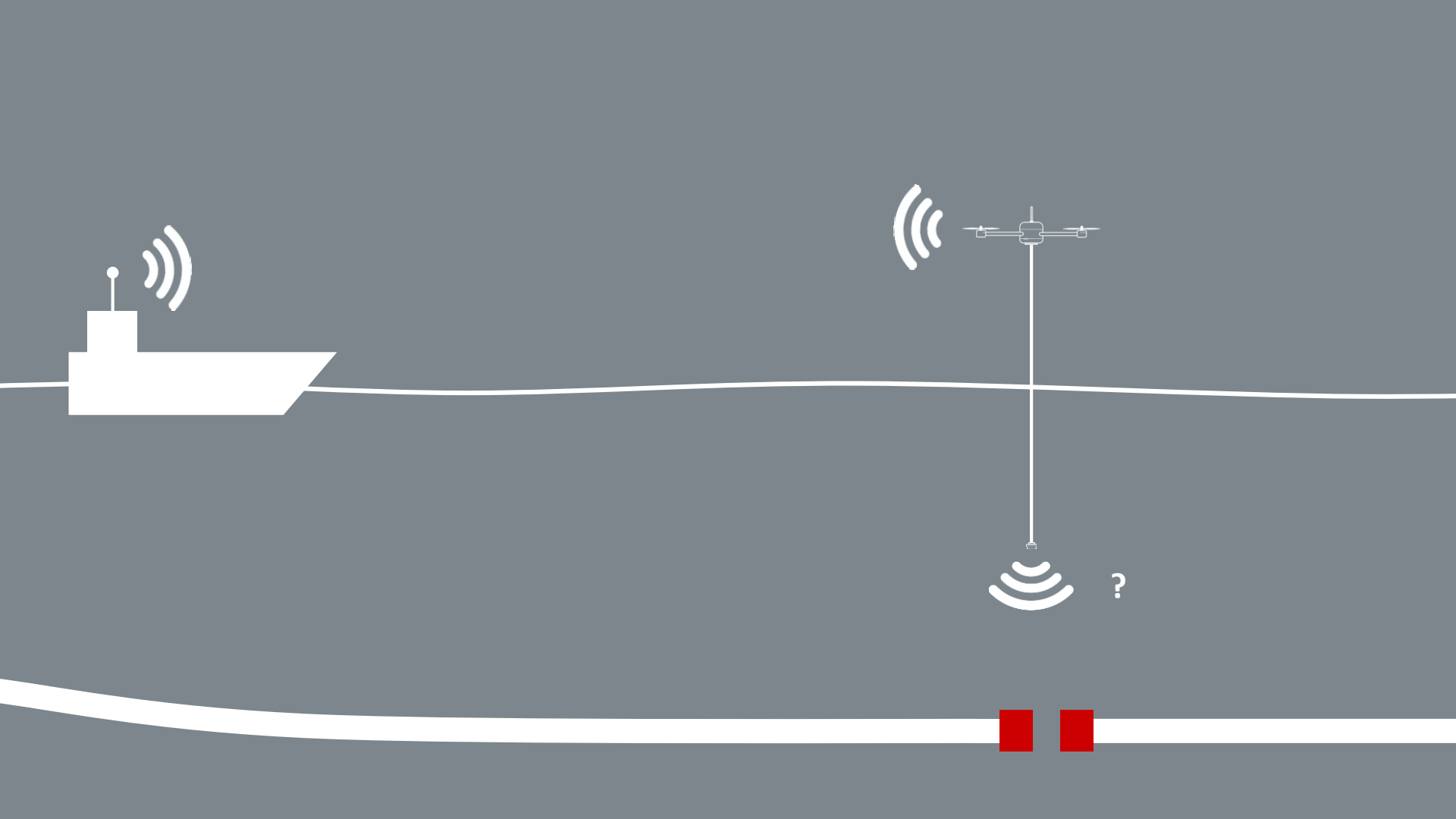


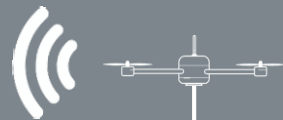


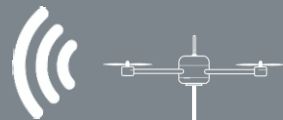
Applications

The background of the slide is a dark, monochromatic photograph of a coastal landscape. In the foreground, a calm body of water reflects the light from the sky. To the right, a steep, dark cliff or shoreline slopes down towards the water. In the background, a range of mountains or hills is visible under a sky filled with soft, textured clouds. The overall mood is serene and somewhat mysterious due to the low light and high contrast.











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